



for Artificial Intelligence

A self-supervised Deep Learning approach for blind denoising of Distributed Acoustic Sensing data

Martijn van den Ende Itzhak Lior Jean-Paul Ampuero Cédric Richard Anthony Sladen André Ferrari





J-invariance (Batson & Royer, ICML '19)

- Suppose we have an input z, for which we can define a partition J
- A *J*-invariant function $g(z)_J$ is one for which the output does not depend on z_J ("*z restricted to J*") for all *z* and partitions *J*
- Zebra example: input z is the picture of the zebra, J is a patch of pixels, and $g(z)_J$ is the prediction of the contents of J

Concept

- Many interesting signals recorded with Distributed Acoustic Sensing are coherent in space and time (earthquakes, ocean waves)
- Incoherent noise (electronic, thermal) can obscure faint signals of interest, and may share a common frequency band
- Separate coherent signals from incoherent noise using J-invariance



DAS data

- Two DAS experiments (18-25 April 2019): HCMR and NESTOR
- During the experiment, several earthquakes were recorded
- Basic pre-processing:
 - Bandpass filtering between 1-10 Hz
 - Downsampling to 50 Hz
 - Cropping to 41-second windows







Original data (1-10 Hz)

Denoised data









Conclusions



- Our approach is entirely **self-supervised**, no "clean" ground truth needed (not available for DAS)
- The Deep Learning model is fast to train and requires little data
- The method separates signals from incoherent noise that share the same frequency band based on spatio-temporal coherence
- Signal coherence improves, which facilitates coherence-based seismological techniques, such as beamforming and template matching

Try it yourself!





Jupyter notebooks (Python) are available at:

doi.org/10.6084/m9.figshare.14152277



A preprint describing the method is available at: doi.org/10.31223/X55K63

