Interaction of Earthquake Characteristics and Fault Mechanics at Various Scales from Observation-Driven Simulations

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# Earthquake source observations encompass various spatial-temporal scales





An earthquake occurs when shear stress on the fault overcomes frictional strength.

## How do earthquakes start, grow and arrest?



Fault stress and strength vary spatially and temporally due to the sliding velocity, fault geometry, material heterogeneity, fluid, etc.

## How do earthquakes start, grow and arrest?



Earthquake rupture stops when fault stress can not overcome frictional strength anymore.

# We use earthquake simulations to understand source physics

- **Dynamic rupture simulations** solve the kinematic rupture process of an earthquake by considering the short-term interaction between fault stress and frictional strength.
- Earthquake cycle simulations solve both the aseismic slip during the interseismic period and the earthquake rupture process when a fault is subjected to slow tectonic loading.

# Overview

- 1. Megathrust earthquakes: Northern Cascadia dynamic rupture scenarios
- 2. Small to moderate earthquakes: Earthquake cycle models with damaged fault zones

Observations Simulations (seismic, geology and geodetic)

# I: Cascadia M9 earthquake

Cascadia Subduction Zone



Little is known about the characteristics of Cascadia M9 earthquake, but a variety of observations are available:

- Plate geometry and velocity structure
- Historical earthquakes and tsunamis
- Locking depth (~12-20km)
- Episodic tremor and slip (ETS) region (~30-40km)
- A gap between the locked region and the ETS region

#### I: Recent results from kinematic rupture simulations



[Frankel et al., 2018; Wirth et al., 2018]

- Ground motions are generated from short rise-time multiple subevents superimposed on a long rise-time slip distribution.
- Shaking intensity depends on the slip distribution, down-dip rupture limit, hypocenter and subevent locations.
- Extending the down-dip rupture limit to the top of the ETS region results in a ~2-3x increase in PGA for Seattle.

# I: 2D Northern Cascadia dynamic rupture

Can we produce more constraints on slip distribution and down-dip rupture extent by incorporating the existing observations in dynamic rupture simulation?



# I: 2D Northern Cascadia dynamic rupture

Shear stress accumulation = stress rate **X** recurrence interval

#### Shear strength = normal stress X friction coefficient



Given a recurrence interval of 500yr, the average shear stress accumulation right above the gap is ~10 Mpa.



#### Model 1: Sharp shear stress gradient at the base of locked zone and dynamic weakening in the gap



100 50 0 -50 X (km)

-100

0

#### Model 2: Model 1 + Slip-neutral friction in the gap





# Summary I: It is the gap region that determines whether down-dip rupture can propagate to the ETS zone in Northern Cascadia.



# II: Earthquakes occur in damaged fault zones



[SAFOD borehole data from Zoback et al., 2011]

# II: DFZ structure varies along depth





#### Model 1: Earthquake cycles in a homogeneous medium



#### Model 2: Earthquake cycles with a DFZ



# Summary II: Seismicity tends to cluster inside damaged fault zones.

A better understanding of fault zone material heterogeneity using dense arrays



# Conclusions

- Northern Cascadia rupture is likely to start near the bottom of locked region due to the concentration of shear stress there. Whether it can propagate to the ETS zone depends on the rheology of the gap region.
- Material heterogeneities like damaged fault zones can cause rupture termination and control seismicity distribution. They generate heterogeneous stress field and earthquakes with a wide range of sizes.